### Rethinking the Camera Pipeline for Computer Vision or, Building an Approximate Camera

Mark Buckler, Cornell Suren Jayasuriya, CMU Adrian Sampson, Cornell

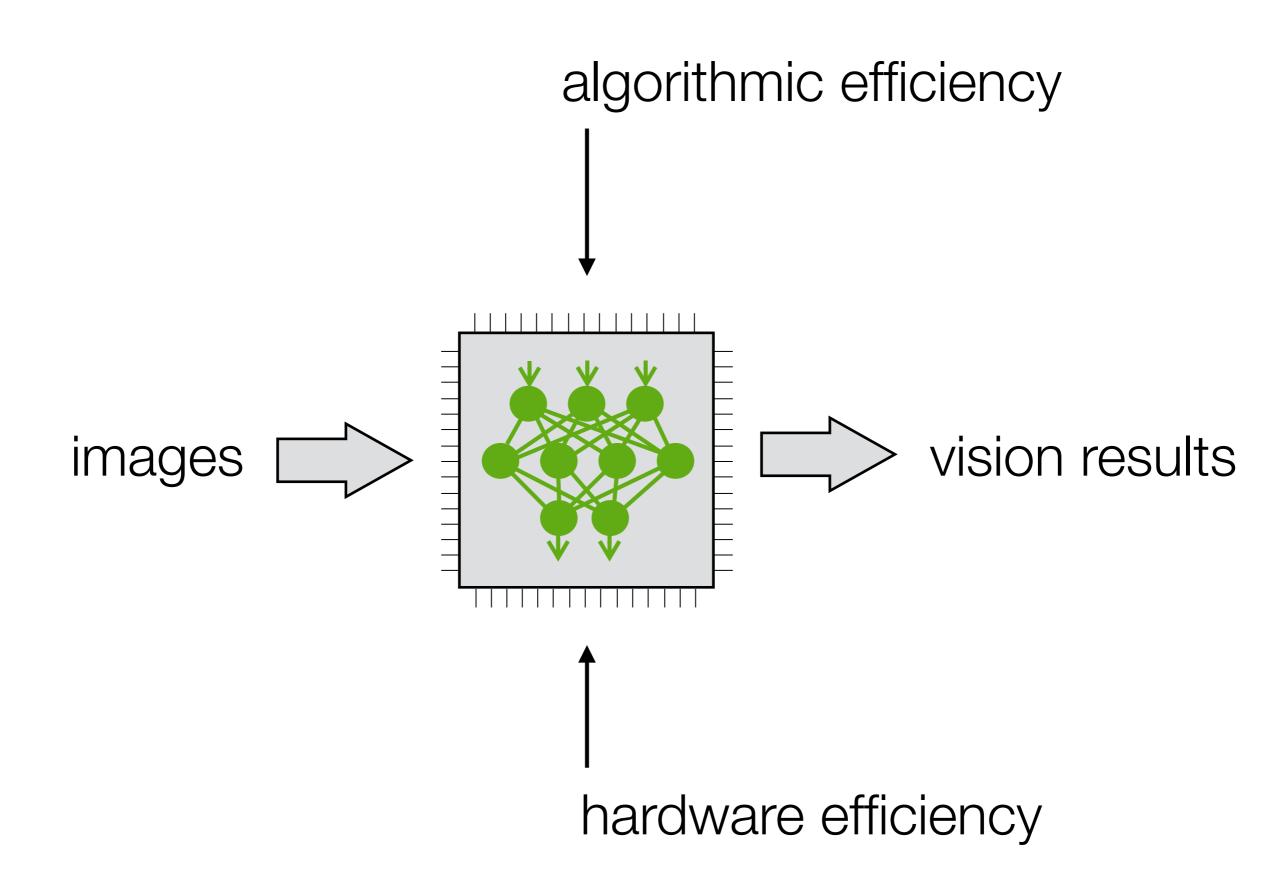
### Mobile vision is a pretty cool idea

object recognition object localization image segmentation 3D structure reconstruction localization & mapping optical character recognition face recognition activity recognition human pose estimation

...always on.

...on your smartphone.

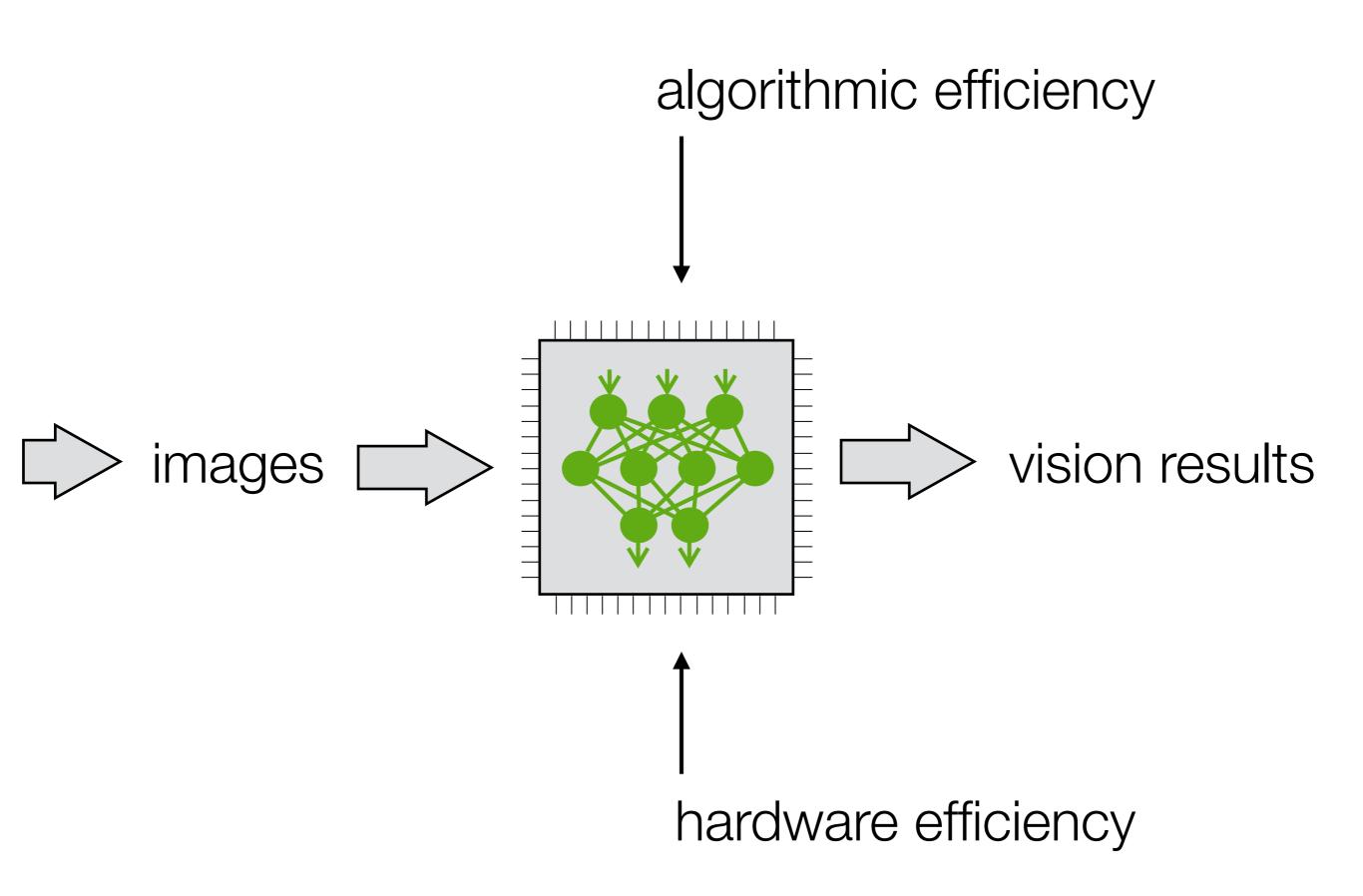
...in real time.

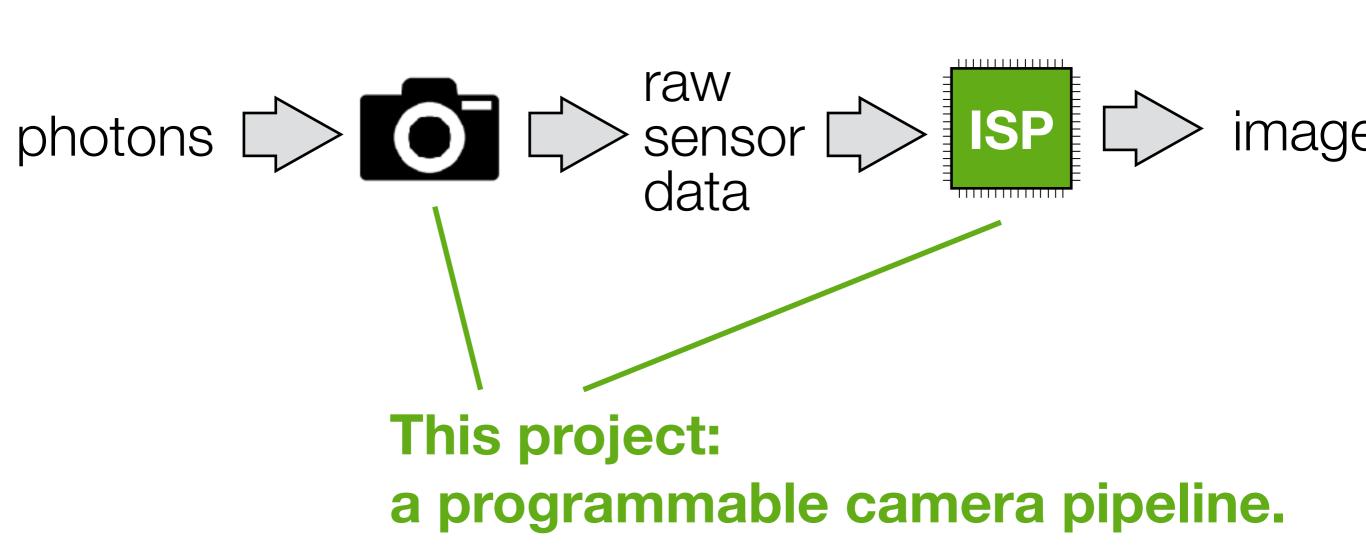


### **ISCA 2016**

<b>11:00am-12:00pm</b> Session 6: Neural Networks 3		10/50411	-11:00um		Collee P
Eyeriss: A Spatial Architecture for Energy-Effi- cient Dataflow for Convolutional Neural Net- works [slides]	Yu-l Joel Vivi	11:00am-12:00pm Session 1A: Neural Networks 1			
Neurocube: A Programmable Digital Neuromor- phic Architecture with High-Density 3D Memo- 	Duc Jaeł ks 2			al-Neuron-Free Deep Convo- etwork Computing <u>[slides]</u>	Jorge Alb Patrick Ju Tayler He
EIE: Efficient Inference En Deep Neural Network [slid		mpressed	Song H Xingyu Huizi M Jing Pu		

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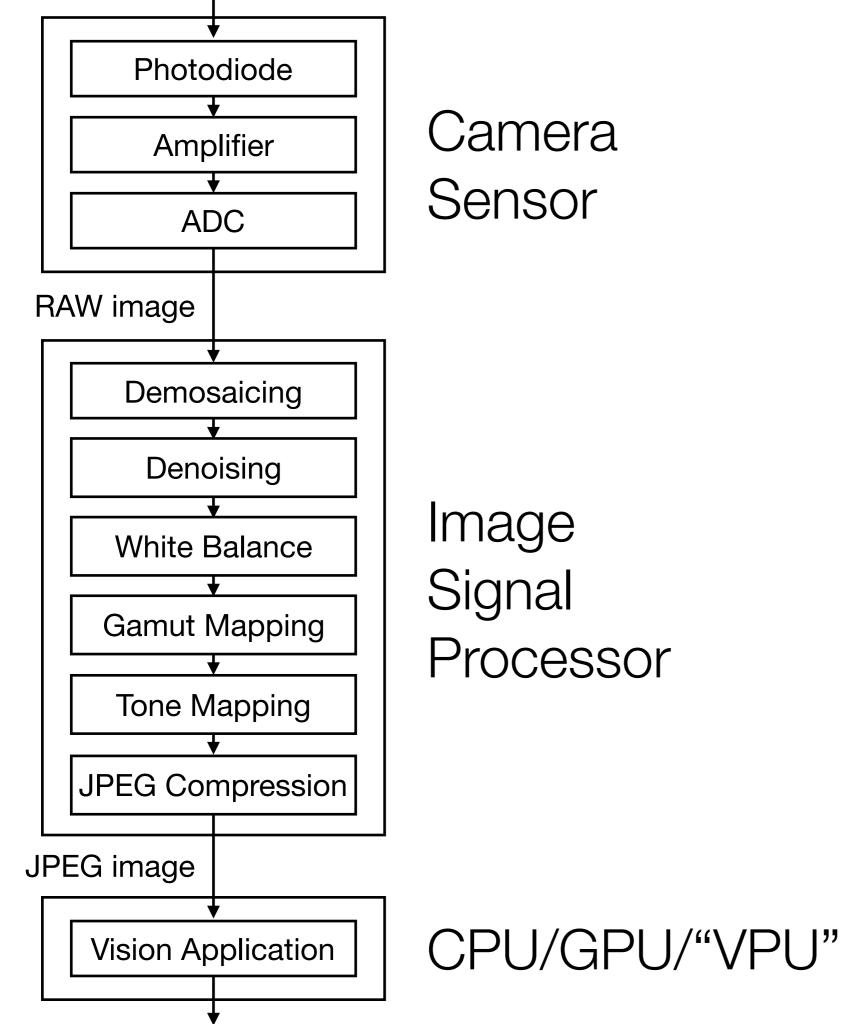


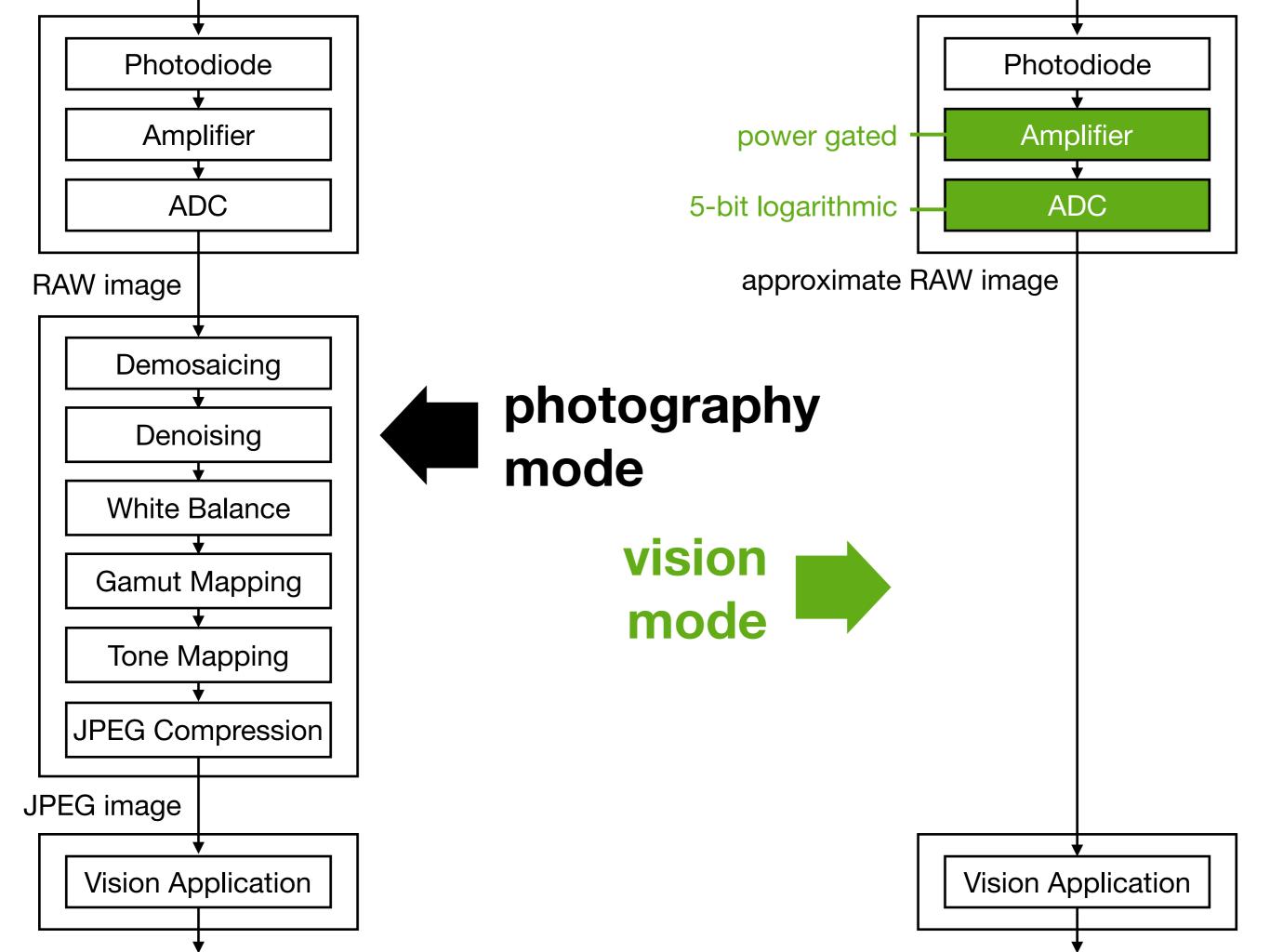
### Let's approximate a camera pipeline

Design **approximation** into the camera sensor and the ISP

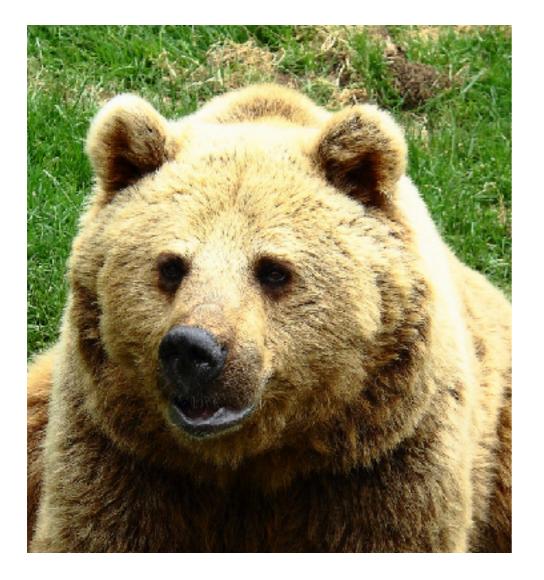
Show how to **retrain** vision models to work on the cheaper, raw data

Measure energy-accuracy **trade-offs** latent in real-world vision applications





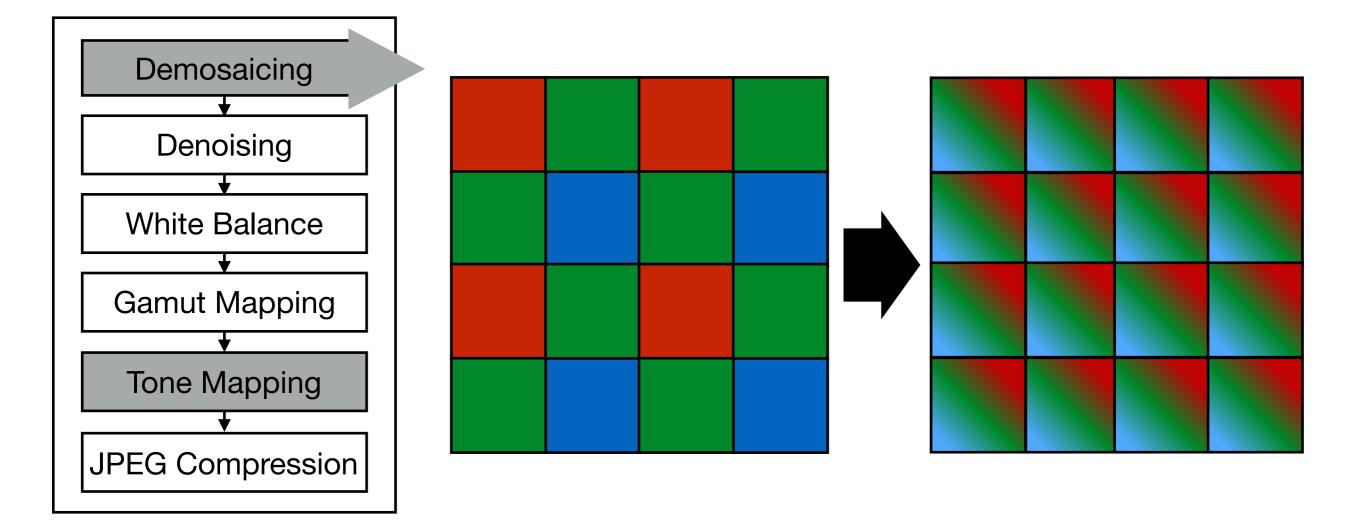
### **Reversing the pipeline**



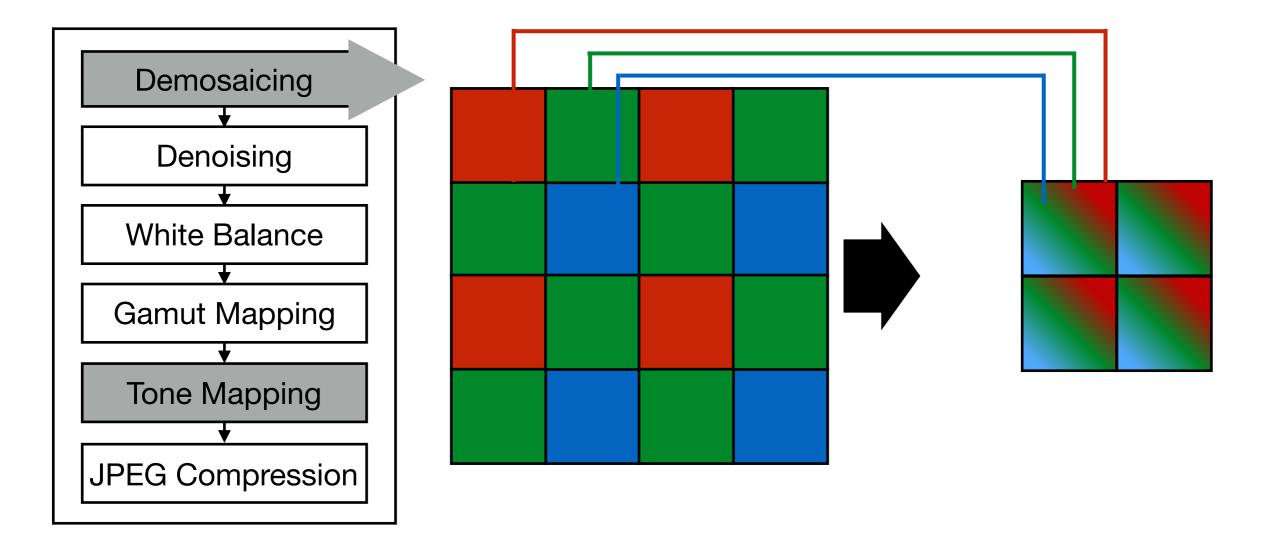


#### **Sensitivity to ISP stages** ResNet20 📕 ResNet44 📕 Farneback 📕 SGBM 📕 OpenMVG 📃 RCNN 📕 OpenFace LeNet3 2 1.75 1.5 normalized error 1.25 1 0.75 0.5 0.25 crash 0 + denoise original demosaic all off + gamma compress

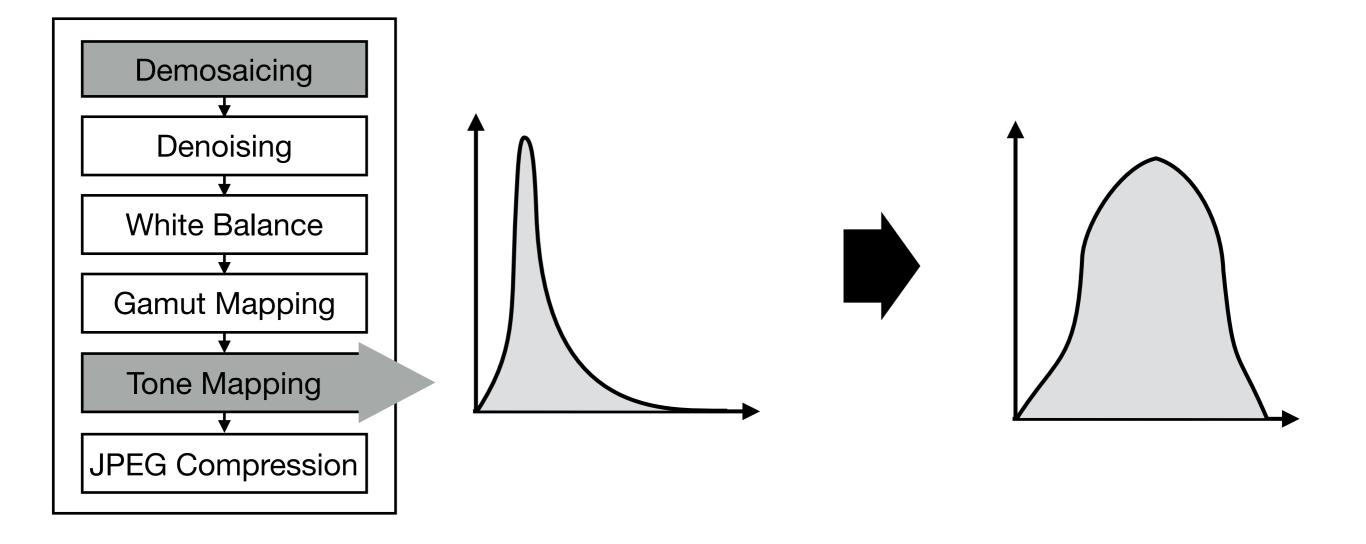
**ISP** pipeline stages

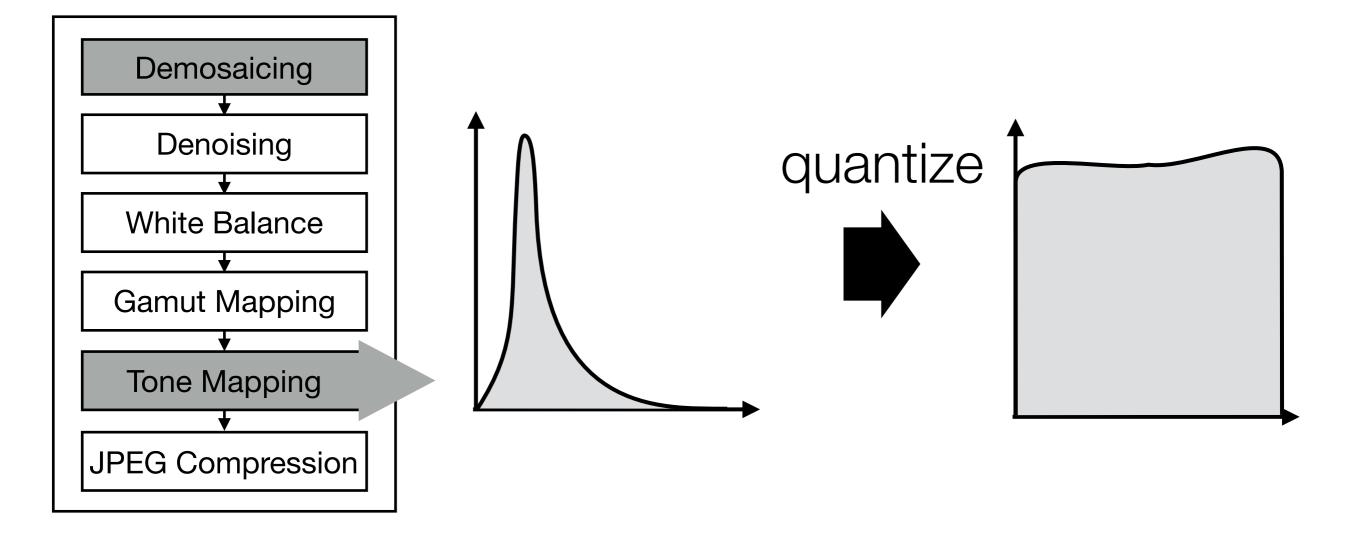


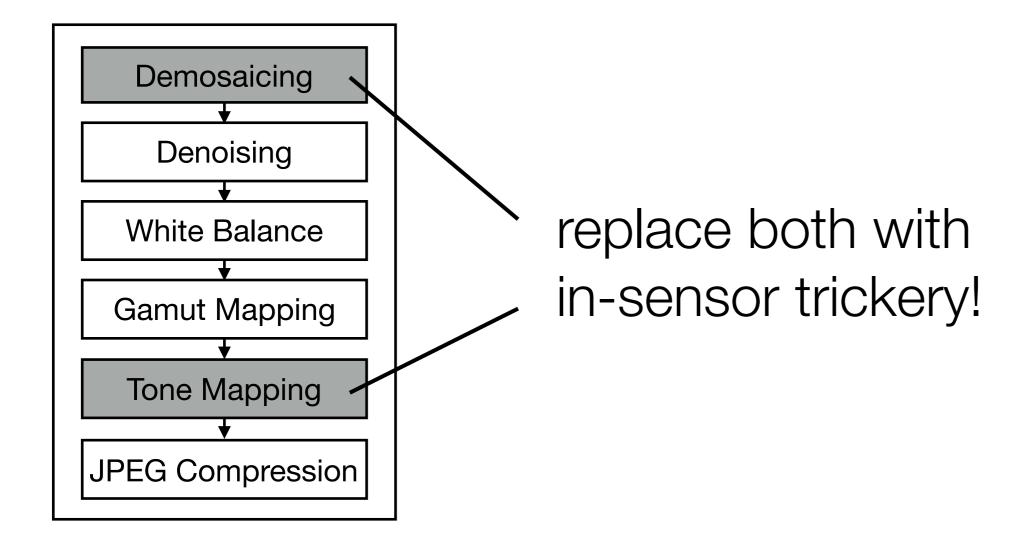
#### "True" demosaicing.



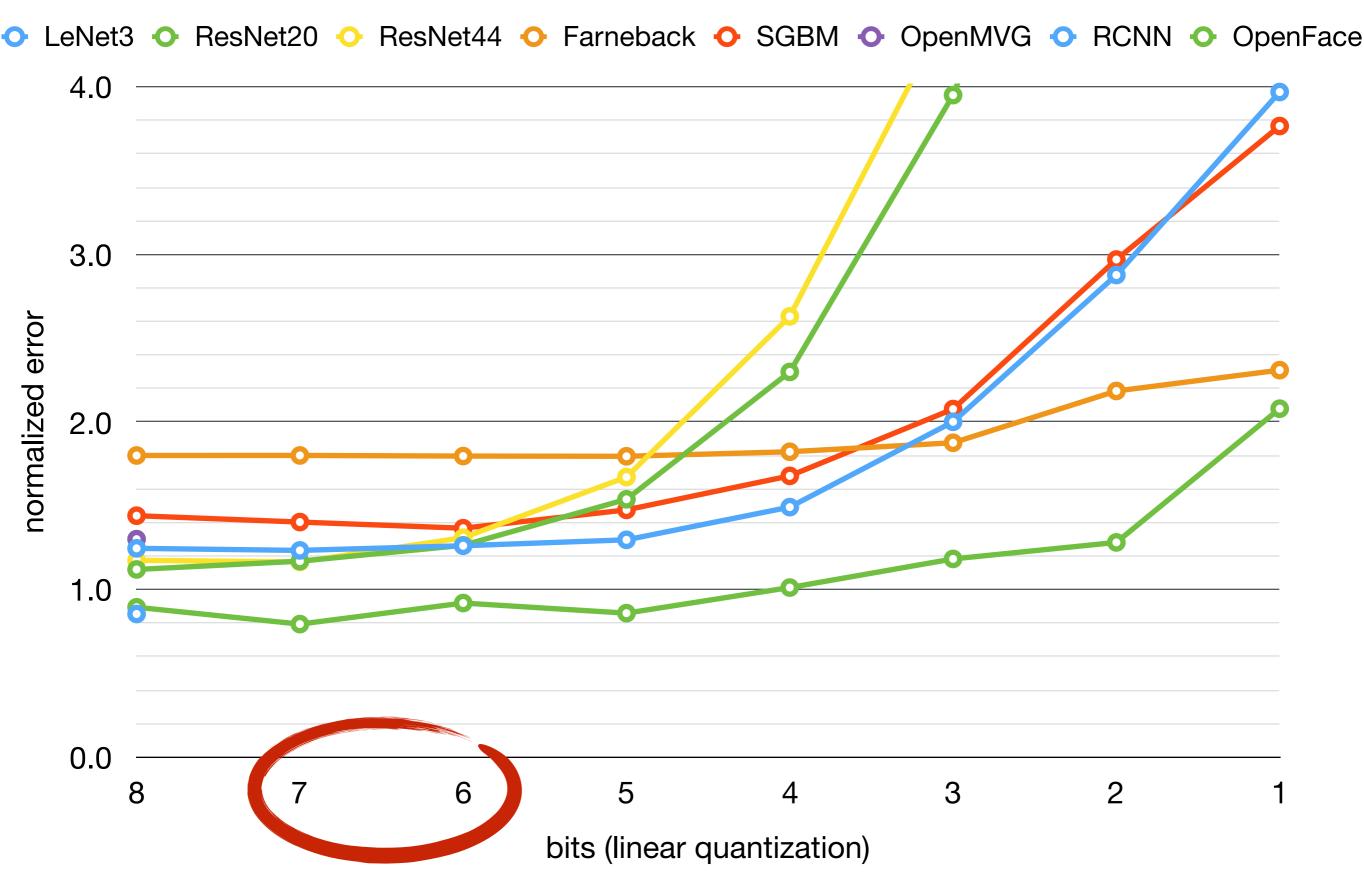
#### Subsampling.



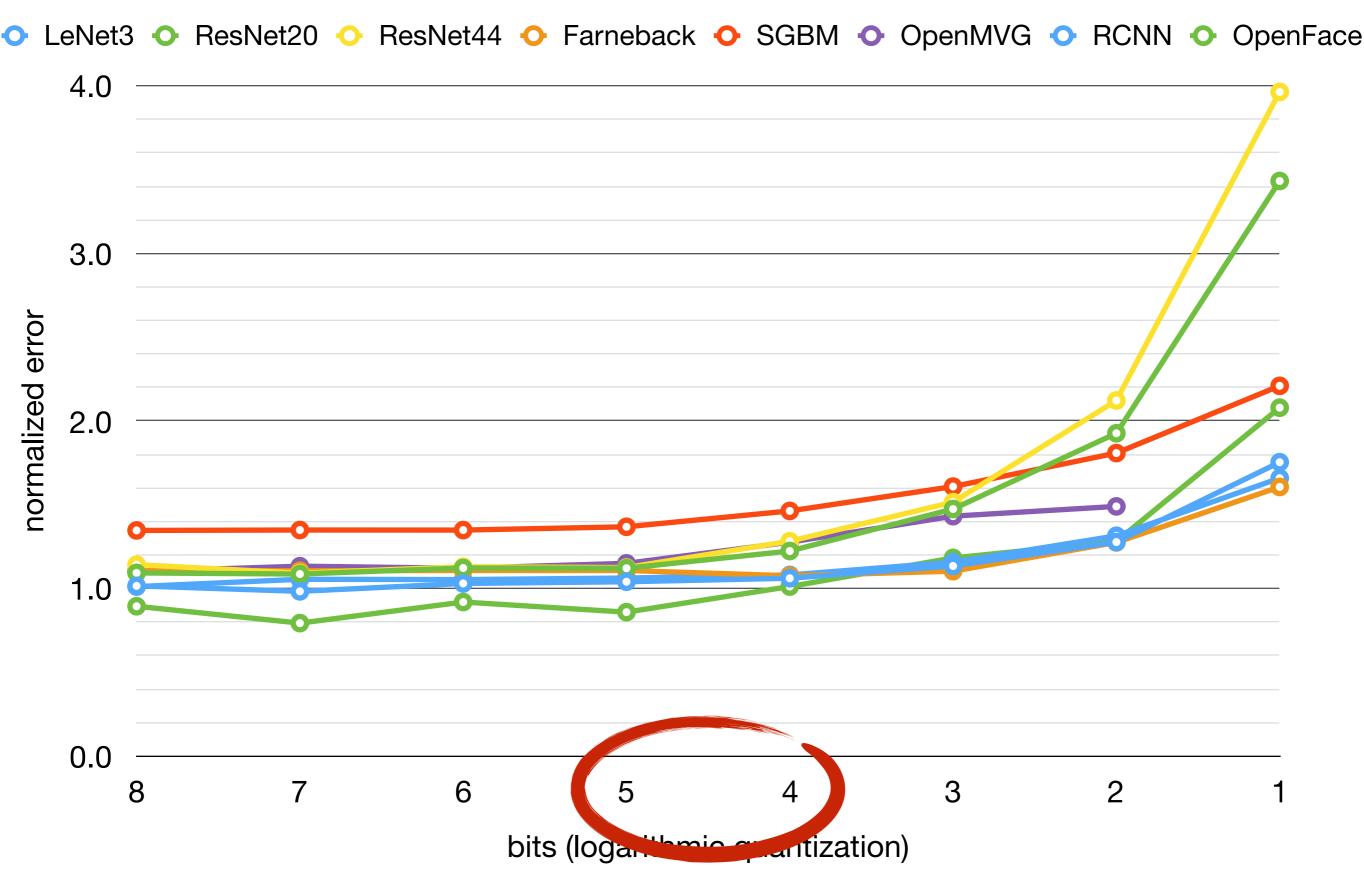


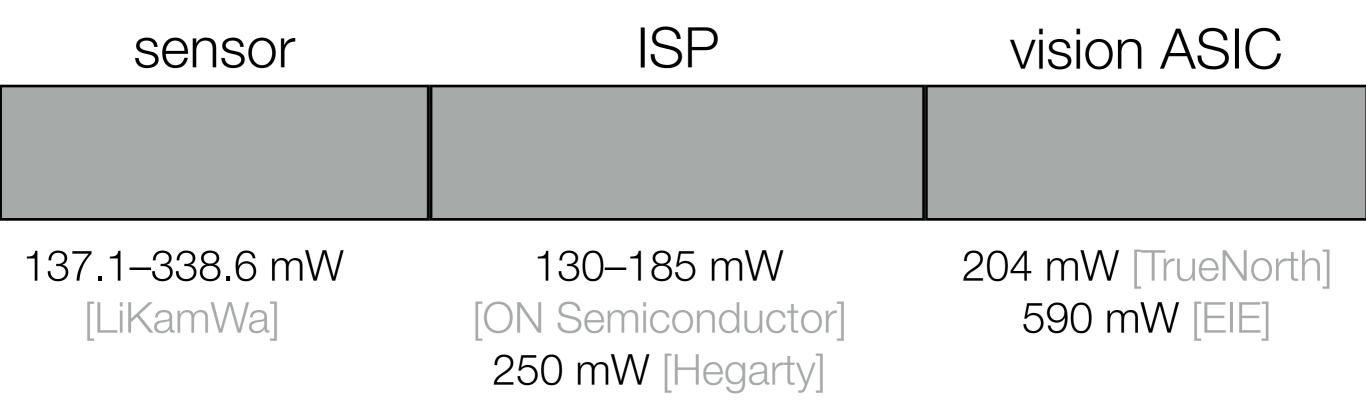


### **Sensitivity to ADC quantization**



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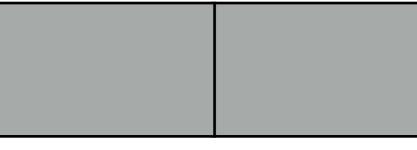












readout (ADCs)









**ISP** 

vision ASIC

#### **Unresolved questions**

Dynamic feedback loop

New signal processing to *improve* learnability

Incremental cost for incremental scene changes

Data movement between sensor, ISP, and application